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# Closed-form expressions for integrals of MKdV and sine-Gordon maps 

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#### Abstract

We present closed-form expressions for approximately $N$ integrals of 2 N dimensional maps. The maps are obtained by travelling wave reductions of the modified Korteweg-de Vries equation and of the sine-Gordon equation, respectively. We provide the integrating factors corresponding to the integrals. Moreover we show how the integrals and the integrating factors relate to the staircase method.


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## 1. Introduction

In recent years, the study of discrete integrable systems has witnessed a revolutionary phase of expansion. Examples of discrete nonlinear equations that are in a certain sense solvable were discovered and the first instances of classification of such systems have appeared [1, 4]. They have applications, e.g. in statistical mechanics, quantum gravity, classical mechanics, solid state physics and in the convergence of algorithms, cf [2, 3, 9, 13].

Two main classes of discrete integrable systems that may be distinguished are integrable partial difference equations $(\mathrm{P} \Delta \mathrm{E})$, and integrable ordinary difference equations $(\mathrm{O} \Delta \mathrm{E})$. The latter are equivalent to integrable mappings. A connection between the two classes is that many integrable maps can be obtained from integrable $\mathrm{P} \triangle$ E's by imposing periodic boundary conditions [6, 7]. In this paper we study (the integrability of) two families of maps obtained in this way from the discrete modified Korteweg-de Vries (MKdV) P $\Delta \mathrm{E}$ and from the sineGordon $\mathrm{P} \Delta \mathrm{E}$, respectively. We present for the first time simple and elegant closed-form expressions for (almost) all their first integrals.

The families of ordinary difference equations, labelled by one integer $p \in \mathbb{N}$, are the modified Korteweg-de Vries O $\Delta \mathrm{E}$

$$
\begin{equation*}
f_{n}:=\alpha_{1}\left(v_{n} v_{n+p}-v_{n+1} v_{n+p+1}\right)+\alpha_{2} v_{n} v_{n+1}-\alpha_{3} v_{n+p} v_{n+p+1}=0, \tag{1}
\end{equation*}
$$

and the sine-Gordon $\mathrm{O} \Delta \mathrm{E}$

$$
\begin{equation*}
\tilde{f}_{n}:=\beta_{1}\left(v_{n} v_{n+p+1}-v_{n+1} v_{n+p}\right)+\beta_{2} v_{n} v_{n+1} v_{n+p} v_{n+p+1}-\beta_{3}=0 . \tag{2}
\end{equation*}
$$

In these equations $\alpha_{i}, \beta_{i}, v_{i} \in \mathbb{R}$, the subscripts on $v$ denote the values of the independent variable. In general we will denote quantities related to the sine-Gordon equation by a superscript wiggle. Both equations is equivalent to a mapping $\mathbb{R}^{p+1} \rightarrow \mathbb{R}^{p+1}$ :

$$
\left(v_{0}, v_{1}, \ldots, v_{p}\right) \mapsto\left(v_{1}, v_{2}, \ldots, v_{p}, v_{p+1}\right)
$$

where we have set $n=0$ and $v_{p+1}$ is given by the solution of either equation (1) or (2):

$$
v_{p+1}=v_{0} \frac{\alpha_{1} v_{p}+\alpha_{2} v_{1}}{\alpha_{1} v_{1}+\alpha_{3} v_{p}}, \quad v_{p+1}=v_{0}^{-1} \frac{\beta_{1} v_{1} v_{p}+\beta_{3}}{\beta_{2} v_{1} v_{p}+\beta_{1}},
$$

respectively. We denote the shift operator by $S$, e.g. we write $S^{j}\left(v_{i}\right)=v_{i+j}$. It is plain that a function $I\left(v_{0}, v_{1}, \ldots, v_{p}\right)$ of $p+1$ variables is an invariant of the mapping obtained from an equation $f\left(v_{0}, v_{1}, \ldots, v_{p+1}\right)=0$ if there is a $\Lambda\left(v_{0}, v_{1}, \ldots, v_{p}\right)$ such that $S(I)-I=f \Lambda$. The functions $I$ and $\Lambda$ are called an integral, and an integrating factor of the equation, or of the mapping, respectively.

In this paper we give closed-form expressions for $\lfloor p / 2\rfloor$ integrals of the MKdV mapping, and $\lceil p / 2\rceil$ integrals of the sine-Gordon mapping. For any even positive $q$ less than $p+1$,

$$
\begin{aligned}
I_{q}^{p}= & \sum_{0 \leqslant c_{1}<c_{2}<\cdots<c_{q-1}<p} \alpha_{1}\left(v_{0} v_{p} \prod_{i=1}^{q-1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}+\frac{1}{v_{0} v_{p}} \prod_{i=1}^{q-1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}\right) \\
& +\sum_{0 \leqslant c_{1}<c_{2}<\cdots<c_{q}<p}\left(\alpha_{2} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}+\alpha_{3} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}\right)
\end{aligned}
$$

is a non-trivial integral of the MKdV mapping. We will show (theorem 1) that $S\left(I_{q}^{p}\right)-I_{q}^{p}=$ $f_{0} \Lambda_{q}^{p}$, with
$\Lambda_{q}^{p}=\sum_{0<c_{1}<c_{2}<\cdots<c_{q-1}<p}\left(\frac{1}{v_{0} v_{1} v_{p} v_{p+1}} \prod_{i=1}^{q-1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}-\prod_{i=1}^{q-1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}\right)$.
These integrals are not new in the sense that an algorithm was previously found by which they can be obtained (although not in this elegant and succinct closed form). This is the staircase method, which we briefly describe in section 4 . We will actually prove that the above integrals, and the integrating factors, are exactly those obtainable by the staircase method.

The sine-Gordon equation has a similar structure as the MKdV equation and it gives similar results. These results will be stated without providing the detailed calculations. The structure of their proofs is the same as for MKdV. For any even non-negative $q$ smaller than $p$,

$$
\begin{aligned}
& \tilde{I}_{q}^{p}=\sum_{0 \leqslant c_{1}<c_{2}<\cdots<c_{q}<p} \beta_{1}\left(\frac{v_{p}}{v_{0}} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}+\frac{v_{0}}{v_{p}} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}\right) \\
&+\sum_{0 \leqslant c_{1}<c_{2}<\cdots<c_{q+1}<p}\left(\beta_{2} \prod_{i=1}^{q+1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}+\beta_{3} \prod_{i=1}^{q+1}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}\right)
\end{aligned}
$$

is a non-trivial integral of the sine-Gordon mapping. We have $S\left(\tilde{I}_{q}^{p}\right)-\tilde{I}_{q}^{p}=\tilde{f}_{0} \tilde{\Lambda}_{q}^{p}$, with $\tilde{\Lambda}_{q}^{p}=\sum_{0<c_{1}<c_{2}<\cdots<c_{q-1}<p}\left(\frac{1}{v_{0} v_{1}} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i+1}}-\frac{1}{v_{p} v_{p+1}} \prod_{i=1}^{q}\left(v_{c_{i}} v_{c_{i}+1}\right)^{(-1)^{i}}\right)$.

## 2. A nice combinatorial object: a multi-sum of products

The following involutive transformation will play a role, $\tau: v_{j} \mapsto v_{j}^{-1}$. The image under $\tau$ of a function $f$ of variables $v_{j}$ will be denoted $f^{\tau}$. In fact both the MKdV and the sine-Gordon equations are invariant under the composition of $\tau$ and interchanging the parameters $\alpha_{2} \leftrightarrow \alpha_{3}$ and $\beta_{2} \leftrightarrow \beta_{3}$, respectively.

Using the following notation, the above integrals and integrating factors can be expressed quite conveniently. We define, with $a, b, n, \epsilon \in \mathbb{Z}$,

$$
\Theta_{n, \epsilon}^{a, b}=\sum_{a \leqslant i_{1}<i_{2}<\cdots<i_{n} \leqslant b} \prod_{j=1}^{n}\left(v_{i_{j}} v_{i_{j}+1}\right)^{(-1)^{j+\epsilon}} .
$$

From the definitions we obtain

- $\Theta_{n, \epsilon+1}^{a, b}=\Theta_{n, \epsilon-1}^{a, b}$,
- $\tau\left(\Theta_{n, \epsilon}^{a, b}\right)=\Theta_{n, \epsilon+1}^{a, b}$,
- $S\left(\Theta_{n, \epsilon}^{a, b}\right)=\Theta_{n, \epsilon}^{a+1, b+1}$,
- $\Theta_{0, \epsilon}^{a, b}=1$,
- $\Theta_{n, \epsilon}^{a, b}=0$ when either $n>\max (0, b-a+1)$ or $n<0$.

Moreover we have the identities

$$
\begin{equation*}
\Theta_{n, \epsilon}^{a, b}=\Theta_{n, \epsilon}^{a+1, b}+\left(v_{a} v_{a+1}\right)^{(-1)^{1+\epsilon}} \Theta_{n-1, \epsilon \pm 1}^{a+1, b} \tag{3}
\end{equation*}
$$

and

$$
\begin{equation*}
\Theta_{n, \epsilon}^{a, b}=\Theta_{n, \epsilon}^{a, b-1}+\left(v_{b} v_{b+1}\right)^{(-1)^{n+\epsilon}} \Theta_{n-1, \epsilon}^{a, b-1} . \tag{4}
\end{equation*}
$$

Our $\Theta$ is a special multi-sum of products, instead of $F_{n}=v_{n} v_{n+1}$ one could take any function $F$ of one variable. Also the latter identities are special cases of more general identities where $\Theta$ 's are expressed as sums of products of $\Theta$ 's. However, the above definition and identities suffice for our purpose.

## 3. The integrals

In this section we prove that the integrals $I_{q}^{p}$ given in the introduction are invariants of the MKdV mapping. This we do by directly calculating the integrating factor that comes with each integral.

In terms of $\Theta$ 's the integrals of the MKdV mapping are

$$
I_{q}^{p}=\alpha_{1}\left(v_{0} v_{p} \Theta_{q-1,0}^{0, p-1}+\frac{1}{v_{0} v_{p}} \Theta_{q-1,1}^{0, p-1}\right)+\alpha_{2} \Theta_{q, 1}^{0, p-1}+\alpha_{3} \Theta_{q, 0}^{0, p-1}
$$

The integrating factors are

$$
\Lambda_{q}^{p}=\frac{1}{v_{0} v_{1} v_{p} v_{p+1}} \Theta_{q-1,1}^{1, p-1}-\Theta_{q-1,0}^{1, p-1}
$$

Theorem 1. For any even positive $q$ less than $p+1$ the expression $I_{q}^{p}$ is a non-trivial integral of the $M K d V$ mapping.

Proof. We show that $S\left(I_{q}^{p}\right)-I_{q}^{p}=f_{0} \Lambda_{q}^{p}$. The $\alpha_{1}$-coefficient of $I_{q}^{p}$ has the form $c+c^{\tau}$ with $c=v_{0} v_{p} \Theta_{q-1,0}^{0, p-1}$. We have, using (3) and (4),

$$
\begin{aligned}
c & =v_{0} v_{p} \Theta_{q-1,0}^{1, p-1}+\frac{v_{p}}{v_{0}} \Theta_{q-2,1}^{1, p-1} \\
& =v_{0} v_{p} \Theta_{q-1,0}^{0, p-2}+\frac{v_{0}}{v_{p-1}} \Theta_{q-2,0}^{0, p-2} .
\end{aligned}
$$

Hence

$$
S(c)=v_{1} v_{p+1} \Theta_{q-1,0}^{1, p-1}+\frac{v_{1}}{v_{p}} \Theta_{q-2,0}^{1, p-1}
$$

and we find that

$$
\begin{aligned}
S\left(c+c^{\tau}\right)-\left(c+c^{\tau}\right) & =\left(v_{1} v_{p+1}-v_{0} v_{p}\right) \Theta_{q-1,0}^{1, p-1}+\left(\frac{1}{v_{1} v_{p+1}}-\frac{1}{v_{0} v_{p}}\right) \Theta_{q-1,1}^{1, p-1} \\
& =\left(v_{0} v_{p}-v_{1} v_{p+1}\right) \Lambda_{q}^{p}
\end{aligned}
$$

For the coefficient of $\alpha_{2}, d=\Theta_{q, 1}^{0, p-1}$, we have

$$
\begin{aligned}
d & =\Theta_{q, 1}^{1, p-1}+v_{0} v_{1} \Theta_{q-1,0}^{1, p-1} \\
& =\Theta_{q, 1}^{0, p-2}+\frac{1}{v_{0} v_{1}} \Theta_{q-1,1}^{0, p-2},
\end{aligned}
$$

and therefore

$$
S(d)=\Theta_{q, 1}^{1, p-1}+\frac{1}{v_{0} v_{1}} \Theta_{q-1,1}^{1, p-1} .
$$

We obtain

$$
S(d)-d=v_{0} v_{1} \Lambda_{q}^{p}
$$

For the coefficient of $\alpha_{3}, d^{\tau}$, we obtain

$$
\begin{aligned}
S\left(d^{\tau}\right)-d^{\tau} & =\left(v_{0} v_{1} \Lambda_{q}^{p}\right)^{\tau} \\
& =v_{p} v_{p+1} \Theta_{q-1,0}^{1, p-1}-\frac{1}{v_{0} v_{1}} \Theta_{q-1,1}^{1, p-1} \\
& =-v_{p} v_{p+1} \Lambda_{q}^{p}
\end{aligned}
$$

Taking these all together we have shown that $S\left(I_{q}^{p}\right)-I_{q}^{p}=f_{0} \Lambda_{q}^{p}$. Finally we note that $I_{0}^{p}=\alpha_{2}+\alpha_{3}, I_{2 p}^{2 p-1}=2$ and $I_{q>p}^{p-1}=0$ are trivial invariants.

## 4. The staircase method

A $\mathrm{P} \Delta \mathrm{E}$ on a two-dimensional lattice

$$
\begin{equation*}
f_{l, m}=f\left(v_{l, m}, v_{l+1, m}, v_{l, m+1}, v_{l+1, m+1}, \ldots\right)=0 \tag{5}
\end{equation*}
$$

with $l, m \in \mathbb{Z}$, has a Lax representation if there are matrices $L, M, N$ depending on a spectral parameter $k$ such that

$$
\begin{equation*}
L_{l, m} M_{l, m}^{-1}-M_{l+1, m}^{-1} L_{l, m+1}=f_{l, m} N_{l, m}, \tag{6}
\end{equation*}
$$

in which $f_{l, m}$ does not depend on $k$, and $N_{l, m}$ is nonsingular on the equation [8]. Note that the right-hand side vanishes for solutions of the equation and is set to 0 by many authors. Similarly, an $O \Delta E$

$$
\begin{equation*}
f_{n}=f\left(v_{n}, v_{n+1}, v_{n+p}, v_{n+p+1}, \ldots\right)=0 \tag{7}
\end{equation*}
$$

with $n \in \mathbb{Z}$, has a Lax representation if there are matrices $\mathcal{L}, \mathcal{M}, \mathcal{N}$ depending on a spectral parameter $k$ such that

$$
\begin{equation*}
\mathcal{M}_{n} \mathcal{L}_{n}-\mathcal{L}_{n+1} \mathcal{M}_{n}=f_{n} \mathcal{N}_{n} \tag{8}
\end{equation*}
$$

A $\mathrm{P} \Delta \mathrm{E}$ can be reduced to an $\mathrm{O} \Delta \mathrm{E}$ through a travelling wave reduction [7]. In the (1, p) travelling wave reduction, which we consider in this paper, the equation and the Lax matrices
depend on the independent variables $l, m$ via the similarity variable $n=l+p m$. Thus we consider periodic solutions of the $\mathrm{P} \Delta \mathrm{E}$ (5) satisfying $v_{l+p, m-1}=v_{l, m}=v_{n}$, which can be obtained from the $\mathrm{O} \Delta \mathrm{E}$ (7).

The staircase method [6,7] provides a way of generating invariants for $\mathrm{O} \Delta \mathrm{Es}$ obtained in this way. The monodromy matrix $\mathcal{L}$ is defined to be the ordered product of Lax matrices along a standard staircase [7]. In the $(1, p)$ reduction the monodromy matrix is

$$
\mathcal{L}_{n}=M_{n}^{-1} \prod_{j=n}^{n+p-1} L_{j}, \quad \text { where } \quad \prod_{j=a}^{\mathfrak{b}} L_{j}:=L_{b} L_{b-1} \cdots L_{a}
$$

With $\mathcal{M}_{n}=L_{n}$ the Lax representation (6) for the $\mathrm{P} \Delta \mathrm{E}$ (5) reduces to the Lax representation (8) for the $\mathrm{O} \Delta \mathrm{E}$ (7), where

$$
\mathcal{N}_{n}=N_{n} \prod_{j=n}^{n+p-1} L_{j}
$$

Multiplying (8) by $-\mathcal{M}_{n}^{-1}$ and taking the trace we obtain that the trace of the monodromy matrix is invariant, that is

$$
\operatorname{tr}\left(\mathcal{L}_{n+1}\right)-\operatorname{tr}\left(\mathcal{L}_{n}\right)=f_{n} \Lambda_{n},
$$

with the integrating factor

$$
\begin{equation*}
\Lambda_{n}=\operatorname{tr}\left(-N_{n} \prod_{j=n+1}^{\substack{n+p-1}} L_{j}\right) \tag{9}
\end{equation*}
$$

One can expand the trace of the monodromy matrix in powers of the spectral parameter. Each coefficient will be an integral of the mapping. And the corresponding integrating factors will be the coefficients of the $k$-expansion of $\Lambda_{n}$.

Both the $\mathrm{MKdV} \mathrm{O} \Delta \mathrm{E}$ and the sine-Gordon $\mathrm{O} \Delta \mathrm{E}$ introduced earlier are derived from integrable $\mathrm{P} \Delta \mathrm{Es}$ by imposing the $(1, p)$ periodicity condition and they inherit a Lax representation. The sine-Gordon $\mathrm{O} \Delta \mathrm{E}(2)$ is obtained from a generalization of the sineGordon $\mathrm{P} \Delta \mathrm{E}$ [7, equation (2)]. The (generalized) reduced Lax matrices for the sine-Gordon equation are, cf [12],

$$
\tilde{M}_{n}^{-1}=\left(\begin{array}{cc}
\beta_{1} \frac{v_{n}}{v_{n+p}} & -\beta_{3} k^{-2} \frac{1}{v_{n+p}} \\
-\beta_{2} v_{n} & \beta_{1}
\end{array}\right), \quad \quad \tilde{L}_{n}=\left(\begin{array}{cc}
1 & -v_{n+1} \\
-k^{2} \frac{1}{v_{n}} & \frac{v_{n+1}}{v_{n}}
\end{array}\right) .
$$

As one easily verifies the reduction of (6) is $\tilde{L}_{n} \tilde{M}_{n}^{-1}-\tilde{M}_{n+1}^{-1} \tilde{L}_{n+p}=\tilde{f}_{n} \tilde{N}_{n}$, with

$$
\tilde{N}_{n}=\left(\begin{array}{cc}
\frac{1}{v_{n+p} v_{n+p+1}} & 0 \\
0 & -\frac{1}{v_{n} v_{n+p}}
\end{array}\right)
$$

As was done for the sine-Gordon equation in [12] one can add parameters in the Lax matrices for the MKdV equation [7, equation A.1]. After an extra gauge transformation we obtain the following reduced Lax matrices,

$$
M_{n}^{-1}=\left(\begin{array}{cc}
\alpha_{3} \frac{v_{n+p}}{v_{n}} & k \\
k & \alpha_{2} \frac{v_{n}}{v_{n+p}}
\end{array}\right), \quad L_{n}=\left(\begin{array}{cc}
\alpha_{1} \frac{v_{n}}{v_{n+1}} & k \\
k & \alpha_{1} \frac{v_{n+1}}{v_{n}}
\end{array}\right) .
$$

We have $L_{n} M_{n}^{-1}-M_{n+1}^{-1} L_{n+p}=f_{n} N_{n}$, with

$$
N_{n}=\left(\begin{array}{cc}
0 & \frac{k}{v_{n+1} v_{n+p}} \\
-\frac{k}{v_{n} v_{n+p+1}} & 0
\end{array}\right) .
$$

Since we have expressed our integrals and integrating factors in terms of the variables $v_{0}, v_{1}, \ldots, v_{p}$, in the sequel we set $n=0$, i.e. we consider $\operatorname{tr}\left(\mathcal{L}_{0}\right)$, and $\Lambda_{0}$. In subsequent sections we will show (theorem 3) that for the MKdV equation the trace of the monodromy matrix is

$$
\operatorname{tr}\left(\mathcal{L}_{0}\right)=\sum_{i=0}^{\lceil p / 2\rceil} I_{2 i}^{p} \alpha_{1}^{p-2 i} k^{2 i}
$$

We also show (theorem 4) that the integrating factor for the MKdV equation is expanded as

$$
\Lambda_{0}=\sum_{i=1}^{\lceil p / 2\rceil} \Lambda_{2 i}^{p} \alpha_{1}^{p-2 i} k^{2 i}
$$

We obtained similar results for the sine-Gordon equation, the trace of its monodromy matrix $\tilde{\mathcal{L}}_{0}$ is

$$
\operatorname{tr}\left(\tilde{\mathcal{L}}_{0}\right)=\sum_{i=0}^{\lfloor p / 2\rfloor} \tilde{I}_{2 i}^{p} k^{2 i}
$$

and the integrating factor $\tilde{\Lambda}_{0}$ of the sine-Gordon equation is

$$
\tilde{\Lambda}_{0}=\sum_{i=0}^{\lfloor p / 2\rfloor} \tilde{\Lambda}_{2 i}^{p} k^{2 i}
$$

## 5. The monodromy matrix

In this section we show that the integrals $I_{q}^{p}$ of the MKdV equation are the coefficients in the $k$-expansion of the trace of its monodromy matrix.

First we give the formula for the expansion of a product of $L$-matrices.
Lemma 2. Let $p \geqslant a \in \mathbb{N}$. We have

$$
\prod_{j=a}^{\mathfrak{p - 1}} L_{j}=\sum_{i=0}^{p-a} Z_{i}^{a, p} \alpha_{1}^{p-a-i} k^{i},
$$

with

$$
Z_{i}^{a, p}=\left(\begin{array}{cc}
\frac{v_{a}}{v_{p}} \Theta_{i, 0}^{a, p-1} & 0 \\
0 & \frac{v_{p}}{v_{a}} \Theta_{i, 1}^{a, p-1}
\end{array}\right)
$$

when $i$ is even and

$$
Z_{i}^{a, p}=\left(\begin{array}{cc}
0 & \frac{1}{v_{a} v_{p}} \Theta_{i, 1}^{a, p-1} \\
v_{a} v_{p} \Theta_{i, 0}^{a, p-1} & 0
\end{array}\right)
$$

when $i$ is odd.
Proof. We expand $L_{n}=\alpha_{1} K_{n}+J k$. It is plain that the $k$-degree of $L_{p-1} L_{p-2} \cdots L_{a}$ is $p-a$. Hence we have

$$
\sum_{i=0}^{p-a} Z_{i}^{a, p} \alpha_{1}^{p-a-i} k^{i}=\left(\alpha_{1} K_{p-1}+J k\right) \sum_{i=0}^{p-a-1} Z_{i}^{a, p-1} \alpha_{1}^{p-a-i-1} k^{i}
$$

Equating coefficients we obtain the following recursive relations:

$$
\begin{aligned}
& Z_{0}^{a, p}=K_{p-1} Z_{0}^{a, p-1} \\
& Z_{i}^{a, p}=K_{p-1} Z_{i}^{a, p-1}+J Z_{i-1}^{a, p-1}, \quad 0<i<p-a \\
& Z_{p-a}^{a, p}=J Z_{p-a-1}^{a, p-1} .
\end{aligned}
$$

From the definition of $\Theta_{n, \epsilon}^{a, b}$ we have that $Z_{0}^{a, a}$ is the identity matrix. Thus, the lemma holds for $p=a, i=0$. Assuming the result for $Z_{0}^{a, p-1}$ we can use the first recursive relation to show that

$$
\begin{aligned}
Z_{0}^{a, p} & =K_{p-1} Z_{0}^{a, p-1} \\
& =\left(\begin{array}{cc}
\frac{v_{p-1}}{v_{p}} & 0 \\
0 & \frac{v_{p}}{v_{p-1}}
\end{array}\right)\left(\begin{array}{cc}
\frac{v_{a}}{v_{p-1}} & 0 \\
0 & \frac{v_{p-1}}{v_{a}}
\end{array}\right) \\
& =\left(\begin{array}{cc}
\frac{v_{a}}{v_{p}} & 0 \\
0 & \frac{v_{p}}{v_{a}}
\end{array}\right)
\end{aligned}
$$

which proves the lemma in the case $i=0$. From the third recursive relation we obtain $Z_{p-a}^{a, p}=J^{p-a}$, in agreement with the lemma. Next, we proceed by induction on two variables, distinguishing the odd and even values of $i$. Assume that the lemma holds for $Z_{i}^{a, p-1}$ and $Z_{i-1}^{a, p-1}$. When $i$ is odd we have

$$
\begin{aligned}
Z_{i}^{a, p} & =K_{p-1} Z_{i}^{a, p-1}+J Z_{i-1}^{a, p-1} \\
& =\left(\begin{array}{cc}
\frac{v_{p-1}}{v_{p}} & 0 \\
0 & \frac{v_{p}}{v_{p-1}}
\end{array}\right)\left(\begin{array}{cc}
0 & \frac{1}{v_{a} v_{p-1}} \Theta_{i, 1}^{a, p-2} \\
v_{a} v_{p-1} \Theta_{i, 0}^{a, p-2} & 0
\end{array}\right)+\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)\left(\begin{array}{cc}
\frac{v_{a}}{v_{p-1}} \Theta_{i-1,0}^{a, p-2} & 0 \\
0 & \frac{v_{p-1}}{v_{a}} \Theta_{i-1,1}^{a, p-2}
\end{array}\right) \\
& =\left(\begin{array}{cc}
0 & \frac{1}{v_{a} v_{p}} \Theta_{i, 1}^{a, p-2}+\frac{v_{p-1}}{v_{a}} \Theta_{i-1,1}^{a, p-2} \\
v_{a} v_{p} \Theta_{i, 0}^{a, p-2}+\frac{v_{a}}{v_{p-1}} \Theta_{i-1,0}^{a, p-2} & 0
\end{array}\right) \\
& =\left(\begin{array}{cc}
0 & \frac{1}{v_{a} v_{p}} \Theta_{i, 1}^{a, p-1} \\
v_{a} v_{p} \Theta_{i, 0}^{a, p-1} & 0
\end{array}\right),
\end{aligned}
$$

where the last equality holds after applying identity (4). When $i$ is even we have

$$
\begin{aligned}
Z_{i}^{a, p} & =K_{p-1} Z_{i}^{a, p-1}+J Z_{i-1}^{a, p-1} \\
& =\left(\begin{array}{cc}
\frac{v_{p-1}}{v_{p}} & 0 \\
0 & \frac{v_{p}}{v_{p-1}}
\end{array}\right)\left(\begin{array}{cc}
\frac{v_{a}}{v_{p-1}} \Theta_{i, 0}^{a, p-2} & 0 \\
0 & \frac{v_{p-1}}{v_{a}} \Theta_{i, 1}^{a, p-2}
\end{array}\right)+\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)\left(\begin{array}{cc}
0 & \frac{1}{v_{a} v_{p-1}} \Theta_{i-1,1}^{a, p-2} \\
v_{a} v_{p-1} \Theta_{i-1,0}^{a, p-2} & 0
\end{array}\right) \\
& =\left(\begin{array}{cc}
\left(\frac{v_{a}}{v_{p}} \Theta_{i, 0}^{a, p-2}+v_{a} v_{p-1} \Theta_{i-1,0}^{a, p-2}\right. & 0 \\
0 & \frac{v_{p}}{v_{a}} \Theta_{i, 1}^{a, p-2}+\frac{1}{v_{a} v_{p-1}} \Theta_{i-1,1}^{a, p-2}
\end{array}\right) \\
& =\left(\begin{array}{cc}
\frac{v_{a}}{v_{p}} \Theta_{i, 0}^{a, p-1} & 0 \\
0 & \frac{v_{p}}{v_{a}} \Theta_{i, 1}^{a, p-1}
\end{array}\right) .
\end{aligned}
$$

Now we can expand the trace of the monodomy matrix.

Theorem 3. The trace of the monodromy matrix of the $M K d V$ equation is

$$
\operatorname{tr}\left(\mathcal{L}_{0}\right)=\sum_{i=0}^{\lceil p / 2\rceil} I_{2 i}^{p} \alpha_{1}^{p-2 i} k^{2 i}
$$

Proof. We expand $M_{0}^{-1}=G_{0} \alpha_{2}+H_{0} \alpha_{3}+J k$. Using lemma 2 we get

$$
\begin{align*}
\operatorname{tr}\left(\mathcal{M}_{0}\right)= & \operatorname{tr} \sum_{i=0}^{p}\left(G_{0} \alpha_{2}+H_{0} \alpha_{3}\right) Z_{i}^{0, p} \alpha_{1}^{p-i} k^{i}+\operatorname{tr} \sum_{i=1}^{p+1} J Z_{i-1}^{0, p} \alpha_{1}^{p-i+1} k^{i} \\
= & \sum_{i=1}^{p} \operatorname{tr}\left(G_{0} \alpha_{2} Z_{i}^{0, p}+H_{0} \alpha_{3} Z_{i}^{0, p}+J Z_{i-1}^{0, p} \alpha_{1}\right) \alpha_{1}^{p-i} k^{i} \\
& +\operatorname{tr}\left(G_{0} \alpha_{2} Z_{0}^{0, p}+H_{0} \alpha_{3} Z_{0}^{0, p}\right) \alpha_{1}^{p}+\operatorname{tr}\left(J Z_{p}^{0, p}\right) k^{p+1} . \tag{10}
\end{align*}
$$

We have $\operatorname{tr}\left(G_{0} \alpha_{2} Z_{0}^{0, p}+H_{0} \alpha_{3} Z_{0}^{0, p}\right)=\alpha_{2}+\alpha_{3}=I_{0}^{p}$ and

$$
\operatorname{tr}\left(J Z_{p}^{0, p}\right)= \begin{cases}0 & p \text { is even } \\ 2=I_{p+1}^{p} & p \text { is odd }\end{cases}
$$

Hence, the $k$-degree of the trace of the monodromy matrix is $2\lceil p / 2\rceil$. Also, the trace in the sum in (10) vanishes for odd values of $i$. When $i$ is even we obtain

$$
\left.\begin{array}{rl}
\operatorname{tr}\left(G_{0} \alpha_{2} Z_{i}^{0, p}\right. & \left.+H_{0} \alpha_{3} Z_{i}^{0, p}+J Z_{i-1}^{0, p} \alpha_{1}\right) \\
= & \operatorname{tr}\left(\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)\left(\begin{array}{cc}
0 & \frac{1}{v_{0} v_{p}} \Theta_{i-1,1}^{0, p-1} \\
v_{0} v_{p} \Theta_{i-1,0}^{0, p-1} & 0
\end{array}\right) \alpha_{1}\right. \\
& +\left(\begin{array}{ll}
0 & 0 \\
0 & \frac{v_{0}}{v_{p}}
\end{array}\right)\left(\begin{array}{cc}
\frac{v_{0}}{v_{p}} \Theta_{i, 0}^{0, p-1} & 0 \\
0 & \frac{v_{p}}{v_{0}} \Theta_{i, 1}^{0, p-1}
\end{array}\right) \alpha_{2} \\
& +\left(\begin{array}{cc}
\frac{v_{p}}{v_{0}} & 0 \\
0 & 0
\end{array}\right)\left(\begin{array}{cc}
\frac{v_{0}}{v_{p}} \Theta_{i, 0}^{0, p-1} & 0 \\
0 & \frac{v_{p}}{v_{0}} \Theta_{i, 1}^{0, p-1}
\end{array}\right) \alpha_{3}
\end{array}\right) .
$$

After a change of variable $i \mapsto 2 i$ the result follows.

## 6. The integrating factors revisited

In this section we show that the integrating factors for the MKdV equation arise as the coefficients in the $k$-expansion of $\Lambda_{0}$, as given by equation (9).

Theorem 4. For the MKdV equation we have the expansion

$$
\Lambda_{0}=\sum_{i=1}^{\lceil p / 2\rceil} \Lambda_{2 i}^{p} \alpha_{1}^{p-2 i} k^{2 i}
$$

Proof. Using lemma 2 with $a=1$ we have

$$
\begin{aligned}
\Lambda_{0} & =\operatorname{tr}\left(-N_{0} \prod_{j=1}^{\curvearrowleft-1} L_{j}\right) \\
& =-\operatorname{tr} \sum_{i=0}^{p-1} N_{0} Z_{i}^{1, p} \alpha_{1}^{p-i-1} k^{i}, \\
& =-\operatorname{tr} \sum_{i=1}^{\lceil p / 2\rceil}\left(\begin{array}{cc}
0 & \frac{1}{v_{1} v_{p}} \\
-\frac{1}{v_{0} v_{p+1}} & 0
\end{array}\right)\left(\begin{array}{cc}
0 & \frac{1}{v_{1} v_{p}} \Theta_{i-1,1}^{1, p-1} \\
v_{1} v_{p} \Theta_{i-1,0}^{1, p-1} & 0
\end{array}\right) \alpha_{1}^{p-2 i} k^{2 i}, \\
& =\sum_{i=1}^{\lceil p / 2\rceil}\left(\frac{1}{v_{0} v_{1} v_{p} v_{p+1}} \Theta_{2 i-1,1}^{1, p-1}-\Theta_{2 i-1,0}^{1, p-1}\right) \alpha_{1}^{p-2 i} k^{2 i},
\end{aligned}
$$

since the product $N_{0} Z_{i}^{1, p}$ vanishes when $i$ is even.

## 7. Discussion

A major question is whether the maps studied in this paper are completely integrable in the Liouville-Arnold sense [2]. A discrete version of the Liouville-Arnold theorem, 5.1 in [11], tells us how many integrals of motion assure integrability of a given symplectic map, and describes the motion on the common level set of these integrals. For a 2 N -dimensional symplectic manifold one needs $N$ functionally independent integrals that are in involution.

In this paper we have provided closed-form expressions for $\lfloor p / 2\rfloor$ integrals of the $(p+1)$-dimensional MKdV mapping, and $\lceil p / 2\rceil$ integrals of the $(p+1)$-dimensional sineGordon mapping. Fortunately, the dimension of the mappings can be reduced by certain transformations [7]. When $p$ is even, the $(p+1)$-dimensional MKdV map can be reduced by one dimension via the transformation $w_{i}=v_{i+1} / v_{i}$ leading to a $p$-dimensional map with $p / 2$ explicit invariants. For $p$ odd, the map can be reduced by two dimensions via the transformation $w_{i}=v_{i+2} / v_{i}$ leading to a $(p-1)$-dimensional map with $(p-1) / 2$ explicit invariants. When $p$ is odd, the $(p+1)$-dimensional sine-Gordon map possesses $(p+1) / 2$ explicit invariants and, for $p$ even, the mapping can be reduced by one dimension via the transformation $w_{i}=v_{i} v_{i+1}$ leading to a $p$-dimensional map with $p / 2$ explicit invariants. In any case we have enough integrals. Explicit expressions for the symplectic structures of these reduced mappings were conjectured in [5]. Symplectic structures, and proofs, for these and for more general reductions can be found in [10].

We were able to verify the functional independence of all the invariants up to dimension 300. The involutivity with respect to the symplectic structures has been checked numerically up to dimension 20. With this evidence at hand it seems almost certain that the maps studied are integrable in the above sense. We have found nice generalizations of identities (3) and (4), which yield explicit formulae for the gradients of the integrals. They will play a role in the general proof, which we hope to publish elsewhere.

We have restricted our discussion to travelling-wave reductions of the lattice variables $l, m$ via the similarity variable $n=l+p m$. It will be interesting to study more general reductions, considering $n=z_{1} l+z_{2} m, z_{1}, z_{2} \in \mathbb{N}$. Another interesting path to pursue will be to consider ultra-discrete versions of the mappings considered.

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